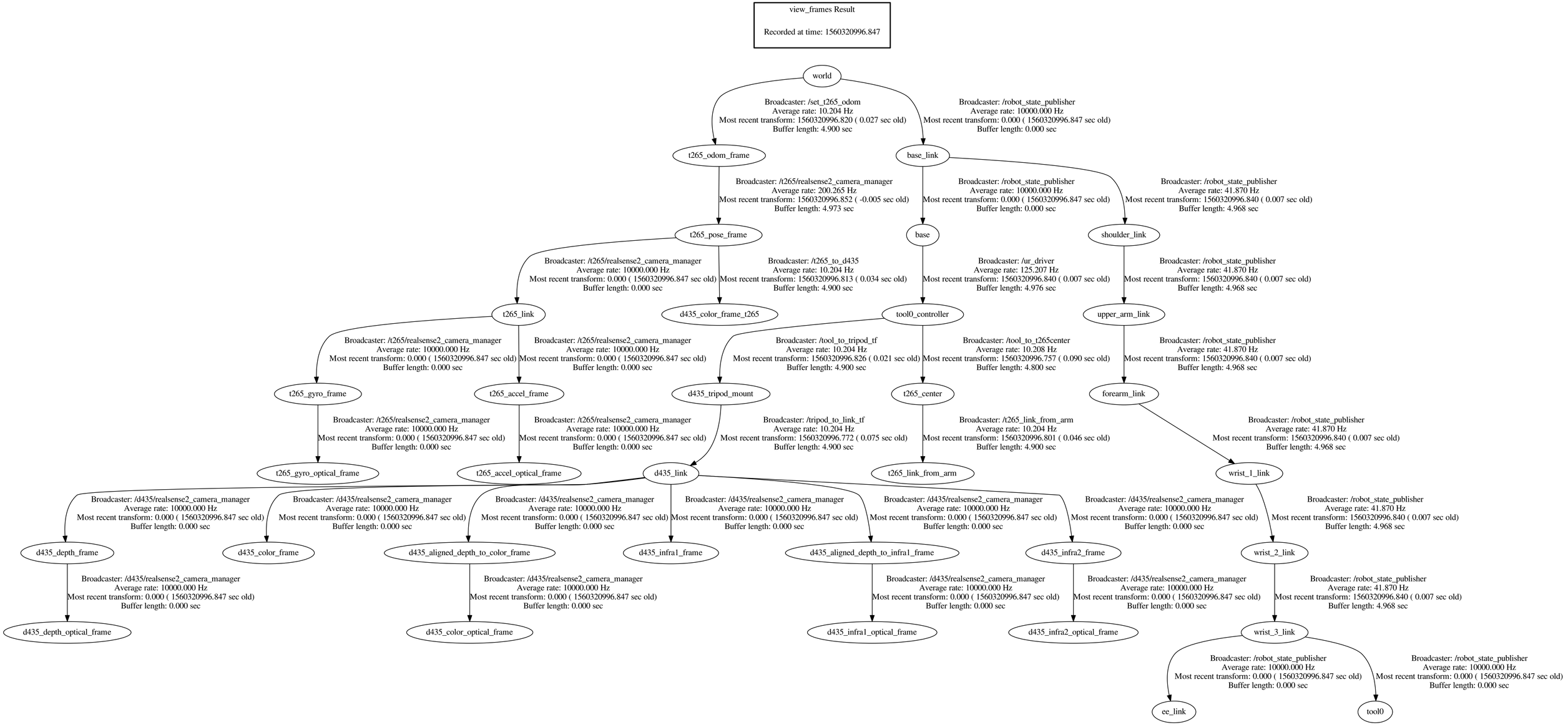
view_frames Result
Recorded at time: 1560320996.847
world
Broadcaster: /set_t265_odom
Average rate: 10.204 Hz
Most recent transform: 1560320996.820 (0.027 sec old)
Buffer length: 4.900 sec
Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1560320996.847 sec old)
Buffer length: 0.000 sec
t265_odom_frame
base_link
Broadcaster: /t265/realsense2_camera_manager
Average rate: 200.265 Hz
Most recent transform: 1560320996.852 (-0.005 sec old)
Buffer length: 4.973 sec
Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1560320996.847 sec old)
Buffer length: 0.000 sec
Broadcaster: /robot_state_publisher
Average rate: 41.870 Hz
Most recent transform: 1560320996.840 (0.007 sec old)
Buffer length: 4.968 sec
t265_pose_frame
base
shoulder_link
Broadcaster: /t265/realsense2_camera_manager
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1560320996.847 sec old)
Buffer length: 0.000 sec
Broadcaster: /t265_to_d435
Average rate: 10.204 Hz
Most recent transform: 1560320996.813 (0.034 sec old)
Buffer length: 4.900 sec
Broadcaster: /ur_driver
Average rate: 125.207 Hz
Most recent transform: 1560320996.840 (0.007 sec old)
Buffer length: 4.976 sec
Broadcaster: /robot_state_publisher
Average rate: 41.870 Hz
Most recent transform: 1560320996.840 (0.007 sec old)
Buffer length: 4.968 sec
t265_link
d435_color_frame_t265
tool0_controller
upper_arm_link
Broadcaster: /t265/realsense2_camera_manager
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1560320996.847 sec old)
Buffer length: 0.000 sec
Broadcaster: /t265/realsense2_camera_manager
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1560320996.847 sec old)
Buffer length: 0.000 sec
Broadcaster: /tool_to_tripod_tf
Average rate: 10.204 Hz
Most recent transform: 1560320996.826 (0.021 sec old)
Buffer length: 4.900 sec
Broadcaster: /tool_to_t265center
Average rate: 10.208 Hz
Most recent transform: 1560320996.757 (0.090 sec old)
Buffer length: 4.800 sec
Broadcaster: /robot_state_publisher
Average rate: 41.870 Hz
Most recent transform: 1560320996.840 (0.007 sec old)
Buffer length: 4.968 sec
t265_gyro_frame
t265_accel_frame
d435_tripod_mount
t265_center
forearm_link
Broadcaster: /t265/realsense2_camera_manager
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1560320996.847 sec old)
Buffer length: 0.000 sec
Broadcaster: /t265/realsense2_camera_manager
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1560320996.847 sec old)
Buffer length: 0.000 sec
Broadcaster: /tripod_to_link_tf
Average rate: 10.204 Hz
Most recent transform: 1560320996.772 (0.075 sec old)
Buffer length: 4.900 sec
Broadcaster: /t265_link_from_arm
Average rate: 10.204 Hz
Most recent transform: 1560320996.801 (0.046 sec old)
Buffer length: 4.900 sec
Broadcaster: /robot_state_publisher
Average rate: 41.870 Hz
Most recent transform: 1560320996.840 (0.007 sec old)
Buffer length: 4.968 sec
t265_gyro_optical_frame
t265_accel_optical_frame
d435_link
t265_link_from_arm
wrist_1_link
Broadcaster: /d435/realsense2_camera_manager
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1560320996.847 sec old)
Buffer length: 0.000 sec
Broadcaster: /d435/realsense2_camera_manager
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1560320996.847 sec old)
Buffer length: 0.000 sec
Broadcaster: /d435/realsense2_camera_manager
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1560320996.847 sec old)
Buffer length: 0.000 sec
Broadcaster: /d435/realsense2_camera_manager
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1560320996.847 sec old)
Buffer length: 0.000 sec
Broadcaster: /d435/realsense2_camera_manager
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1560320996.847 sec old)
Buffer length: 0.000 sec
Broadcaster: /d435/realsense2_camera_manager
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1560320996.847 sec old)
Buffer length: 0.000 sec
Broadcaster: /robot_state_publisher
Average rate: 41.870 Hz
Most recent transform: 1560320996.840 (0.007 sec old)
Buffer length: 4.968 sec
d435_depth_frame
d435_color_frame
d435_aligned_depth_to_color_frame
d435_infra1_frame
d435_aligned_depth_to_infra1_frame
d435_infra2_frame
wrist_2_link
Broadcaster: /d435/realsense2_camera_manager
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1560320996.847 sec old)
Buffer length: 0.000 sec
Broadcaster: /d435/realsense2_camera_manager
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1560320996.847 sec old)
Buffer length: 0.000 sec
Broadcaster: /d435/realsense2_camera_manager
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1560320996.847 sec old)
Buffer length: 0.000 sec
Broadcaster: /d435/realsense2_camera_manager
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1560320996.847 sec old)
Buffer length: 0.000 sec
Broadcaster: /robot_state_publisher
Average rate: 41.870 Hz
Most recent transform: 1560320996.840 (0.007 sec old)
Buffer length: 4.968 sec
d435_depth_optical_frame
d435_color_optical_frame
d435_infra1_optical_frame
d435_infra2_optical_frame
wrist_3_link
Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1560320996.847 sec old)
Buffer length: 0.000 sec
Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1560320996.847 sec old)
Buffer length: 0.000 sec
ee_link
tool0